

$$(AB)_{ij} = \sum_{n=1}^N A_{in} B_{nj}, \quad (\text{B.37})$$

Transpose

and the *transpose*  $(A^\top)_{ij} := A_{ji}$ .

Inverse and

Pseudo-Inverse

The *inverse* of a matrix  $A$  is written  $A^{-1}$  and satisfies  $AA^{-1} = A^{-1}A = \mathbf{1}$ . The *pseudo-inverse*  $A^\dagger$  satisfies  $AA^\dagger A = A$ . While every matrix has a pseudo-inverse, not all have an inverse. Those which do are called *invertible* or *nonsingular*, and their inverse coincides with the pseudo-inverse. Sometimes, we simply use the notation  $A^{-1}$ , and it is understood that we mean the pseudo-inverse whenever  $A$  is not invertible.

### B.2.2 Norms and Dot Products

Thus far, we have explained the linear structure of spaces such as the feature space induced by a kernel. We now move on to the *metric* structure. To this end, we introduce concepts of length and angles.

**Definition B.5 (Norm)** A function  $\|\cdot\| : \mathcal{H} \rightarrow \mathbb{R}_0^+$  that for all  $\mathbf{x}, \mathbf{x}' \in \mathcal{H}$  and  $\lambda \in \mathbb{R}$  satisfies

$$\|\mathbf{x} + \mathbf{x}'\| \leq \|\mathbf{x}\| + \|\mathbf{x}'\|, \quad (\text{B.38})$$

$$\|\lambda \mathbf{x}\| = |\lambda| \|\mathbf{x}\|, \quad (\text{B.39})$$

$$\|\mathbf{x}\| > 0 \text{ if } \mathbf{x} \neq \mathbf{0}, \quad (\text{B.40})$$

Norm

is called a *norm* on  $\mathcal{H}$ . If we replace the “ $>$ ” in (B.40) by “ $\geq$ ,” we are left with what is called a *semi-norm*.

Metric

Any norm defines a *metric*  $d$  via

$$d(\mathbf{x}, \mathbf{x}') := \|\mathbf{x} - \mathbf{x}'\|; \quad (\text{B.41})$$

likewise, any semi-norm defines a *semi-metric*. The (semi-)metric inherits certain properties from the (semi-)norm, in particular the triangle inequality (B.38) and positivity (B.40).

While every norm gives rise to a metric, the converse is not the case. In this sense, the concept of the norm is stronger. Similarly, every *dot product* (to be introduced next) gives rise to a norm, but not vice versa.

Before describing the dot product, we start with a more general concept.

**Definition B.6 (Bilinear Form)** A bilinear form on a vector space  $\mathcal{H}$  is a function

$$Q : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R} \\ (\mathbf{x}, \mathbf{x}') \rightarrow Q(\mathbf{x}, \mathbf{x}') \quad (\text{B.42})$$

with the property that for all  $\mathbf{x}, \mathbf{x}', \mathbf{x}'' \in \mathcal{H}$  and all  $\lambda, \lambda' \in \mathbb{R}$ , we have

$$Q((\lambda \mathbf{x} + \lambda' \mathbf{x}'), \mathbf{x}'') = \lambda Q(\mathbf{x}, \mathbf{x}'') + \lambda' Q(\mathbf{x}', \mathbf{x}''), \quad (\text{B.43})$$

$$Q(\mathbf{x}'', (\lambda \mathbf{x} + \lambda' \mathbf{x}')) = \lambda Q(\mathbf{x}'', \mathbf{x}) + \lambda' Q(\mathbf{x}'', \mathbf{x}'). \quad (\text{B.44})$$